Thermally Conducting Fluid Flow of an Unsteady MHD Third Order Fluid between Two Vertical Oscillating Plates

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ABSTRACT

The flow of magnetohydrodynamic unsteady third grade fluid problem is examined between two vertical and oscillating parallel plates. The parallel plates are oscillating and the fluid drain down due to gravity. A uniform magnetic field is applied perpendicularly to the plates in the presence of temperature field. The model differential equations are solved analytically by using Adomain Decomposition Method (ADM). The effects of various physical parameters are discussed graphically.

KEYWORDS: Unsteady, MHD, Temperature Field, Adomain Decomposition Method (ADM).

INTRODUCTION

Considerable attention has been paid in recent years to problems of flow of non-Newtonian fluids. The flows of MHD incompressible non Newtonian fluid involving heat transfer have many practical applications in the modern technology and industries. For example, compression or absorption plant and heat pumps, the cooling water circulated through a gasoline or diesel engine, MHD power generators, accelerators, polymer and petroleum industries. Over the past few decades, there has been growing recognition of the fact that many fluids of industrial significance do not obey the Newtonian postulate of linear relationship between the shear stress and shear rate. Therefore, these fluids are known as non-Newtonian fluids. Common examples of such fluids are slurries, pastes, gels, molten plastics and lubricants containing polymer additives. The unsteady flow of Non-Newtonian fluid was discussed in [1,7]. Qayyum Shah et al in [8] have investigated gravity driven flow of an unsteady second order fluid between two parallel and vertical oscillating plates. Taza Gul et al [9] observed a heat transfer analysis of MHD thin film flow of an unsteady second grade fluid past a vertical oscillating belt. Sidra Abid et al [10] discussed an unsteady second grade fluid between two vertical plates with oscillating boundary conditions. A thin film flow of unsteady third grade fluid between two vertical plates when one of the plates oscillating and the other is stationary was discussed in [11,13]. Taza Gul et al [14] have observed a temperature dependent viscosity of thin film flow of third grade fluid on a vertical belt. Ali et al [15] has investigated a Laplace transform method for unsteady thin film flow of a second grade fluid through a porous medium. Unsteady MHD Couette Flow between Two Infinite Parallel Porous Plates in an Inclined Magnetic Field with Heat Transfer was discussed in [16, 20].

For the solution of nonlinear differential equation, various method are used. Aamer Khan et al [21] have observed OHAM Solution for the non-linear differential equation. Mabood et al [22] used Optimal Homotopy Asymptotic Method for the solution of differential equation. Adomian decomposition method for solving boundary value problems for higher order nonlinear differential equations was used in [23, 26].

In the present article we will use Adomian decomposition method (ADM) for the solution of nonlinear differential equations of gravity driven flow of an unsteady third order fluid between two parallel and vertical oscillating plates.

Basic equations

The MHD equations which govern the unsteady incompressible flow of third grade fluid are

\[ \mathbf{V} = (0, v(x, t), 0), \]

\[ \Theta = \Theta(x, t). \]

Subject to the following boundary conditions as

\[ v(h, t) = V \cos \omega t, \quad v(-h, t) = V \cos \omega t \]

\[ \Theta(h, t) = \Theta_0, \quad \Theta(-h, t) = \Theta_1, \]
Here\(v(x, t), \Theta(x, t)\), are the velocity and temperature components in x-direction where \(\omega\) is the frequency of the oscillating belt.

The Cauchy stress tensor \(\mathbf{T}\), for the third grade fluid model is

\[
\mathbf{T} = -\mathbf{p} \mathbf{I} + \mu \mathbf{A}_1 + \alpha_1 \mathbf{A}_2 + \alpha_2 \mathbf{A}_2^2 + \beta_1 \mathbf{A}_3 + \beta_2 (\mathbf{A}_1 \mathbf{A}_2 + \mathbf{A}_2 \mathbf{A}_1) + \beta_3 (\text{tr} \mathbf{A}_1^2) \mathbf{A}_1
\]

Where \(\mathbf{I}\) is identity tensor, \(p\) is fluid pressure, \(\mu\) is the coefficient of viscosity, \(\alpha_1(i = 1, 2), \beta_1(j = 1, 2, 3)\), are the material constants second grade and third grade fluids. The first four Rivlin-Erick tensors \(\mathbf{A}_m(m = 1, 2, 3, 4)\) are defined by the following relations

\[
\mathbf{A}_0 = \mathbf{I}, \quad \mathbf{A}_1 = \mathbf{L} + \mathbf{L}^T, \quad \mathbf{L} = \text{grad} (\mathbf{v}), \quad \mathbf{A}_n = \frac{\partial \mathbf{A}_{n-1}}{\partial t} + \mathbf{A}_{n-1} (\mathbf{L}) + (\mathbf{L})^T \mathbf{A}_{n-1}, \quad n = 2, 3, 4.
\]

For the electrically conducting unsteady incompressible third grade fluid flow with body the continuity and momentum equations are

\[
\text{div} \mathbf{V} = 0, \tag{9}
\]

\[
\rho \frac{\partial \mathbf{v}}{\partial t} = \text{div} \mathbf{T} + \rho g + \mathbf{J} \times \mathbf{B}, \tag{10}
\]

\[
\nabla \cdot \mathbf{B} = 0, \quad \nabla \times \mathbf{B} = \mu_0 
\mathbf{J}, \quad \mathbf{J} = \sigma (\mathbf{E} + \mathbf{v} \times \mathbf{B}), \tag{12}
\]

\[
\mathbf{J} \times \mathbf{B} = [0, -\sigma \mathbf{B}_0 v(x, 0)]. \tag{13}
\]

Where \(\rho\) is the fluid density, \(\mathbf{J}\) is the current density, \(\mathbf{B} = (0, B_0, 0)\) is the uniform magnetic field, \(\sigma\) is the electrical conductivity, \(\mu_0\) is the magnetic permeability. \(\mathbf{E}\) and \(\mathbf{B}\) are electric and magnetic fields, \(\sigma\) is the material time derivative, \(g\) is the external body force, \(k\) is the thermal conductivity and \(c_p\), is specific heat.

Using Eq. (1), the continuity Eq. (9), is identically satisfied and Eqs. (10, 11) reduced to the form

\[
\rho \frac{\partial \mathbf{v}}{\partial t} = \frac{\partial}{\partial x} \left( \rho \mathbf{v} \frac{\partial \mathbf{v}}{\partial x} \right) - \rho g - \sigma B_0^2 \mathbf{v} \tag{14}
\]

The component of Cauchy stress \(T_{xy}\), obtained

\[
T_{xy} = \mu \frac{\partial \mathbf{v}}{\partial x} + \alpha_1 \frac{\partial}{\partial t} \left( \frac{\partial \mathbf{v}}{\partial x} \right) + \beta_1 \frac{\partial^2 \mathbf{v}}{\partial t^2} \left( \frac{\partial \mathbf{v}}{\partial x} \right) + 2(\beta_2 + \beta_3) \left( \frac{\partial^3 \mathbf{v}}{\partial t^3} \right) \left( \frac{\partial \mathbf{v}}{\partial x} \right)^2. \tag{16}
\]

Substituting Eq.(16) in momentum Eq.(15), we get

\[
\rho \frac{\partial \mathbf{v}}{\partial t} = \mu \frac{\partial^2 \mathbf{v}}{\partial x^2} + \alpha_1 \frac{\partial}{\partial t} \left( \frac{\partial^2 \mathbf{v}}{\partial x^2} \right) + 12(\beta_2 + \beta_3) \left( \frac{\partial^3 \mathbf{v}}{\partial t^3} \right) \left( \frac{\partial \mathbf{v}}{\partial x} \right)^2 - \rho g - \sigma B_0^2 \mathbf{v}. \tag{17}
\]

Heat equation become

\[
\rho c_p \frac{\partial \Theta}{\partial t} = k \left( \frac{\partial^2 \Theta}{\partial x^2} \right) + \mu \left( \frac{\partial^2 \mathbf{v}}{\partial x^2} \right)^2 + \alpha_1 \left( \frac{\partial^2 \mathbf{v}}{\partial x \partial t} \right) \left( \frac{\partial \mathbf{v}}{\partial x} \right) + \beta_1 \left( \frac{\partial^2 \mathbf{v}}{\partial t \partial x} \right) \left( \frac{\partial \mathbf{v}}{\partial x} \right) + 2(\beta_2 + \beta_3) \left( \frac{\partial^3 \mathbf{v}}{\partial t^3} \right) \left( \frac{\partial \mathbf{v}}{\partial x} \right)^2. \tag{18}
\]

We are introducing some non-dimensional quantities as follows

\[
\overline{\mathbf{v}} = \frac{\mathbf{v}}{\mathbf{V}}, \quad \overline{x} = x / \delta, \quad \overline{t} = \frac{t \mu}{\delta^2}, \quad \overline{\mathbf{A}}_1 = \frac{\alpha_1}{\rho \delta^2}, \quad \overline{\mathbf{A}}_2 = \frac{\beta_1 \mu}{\delta^2}, \quad \overline{\mathbf{A}}_3 = \frac{(\beta_2 + \beta_3) V^2}{\mu \delta^2}, \tag{19}
\]

where \(S_t = \frac{\rho \delta^2 \beta}{\mu}, \quad P_r = \frac{c_p \mathbf{v}}{k}, \quad \overline{\Theta} = \frac{\Theta - \Theta_0}{\Theta_1 - \Theta_2}, \quad E_c = \frac{\beta}{\rho \delta^2}, \quad \overline{\mathbf{v}}(x, t) = \cos \omega t, \quad \overline{\mathbf{v}}(-x, t) = \cos \omega t. \tag{22}
\]
2.2 Basic concepts of Adomain Decomposition Method (ADM)

We consider a nonlinear partial differential equation in an operator form as

\[ A_x v(x,t) + A_t v(x,t) + S v(x,t) + N v(x,t) = g(x,t), \]  
\[ A_x^2 v(x,t) = g(x,t) - A_t v(x,t) - S v(x,t) - N v(x,t). \]

Where \( A_x = \frac{\partial^2}{\partial x^2} \) and \( A_t = \frac{\partial}{\partial t} \) are linear operators in the partial differential equation and are easily invertible, \( g(x,t) \) is a source term, \( Rv(x,t) \) is a remaining linear term and \( N v(x,t) \) is non-linear analytical term expandable in the adomian polynomials \( A_n \).

Taking the inverse operator \( A_x^{-1} \) to both sides of Eq. (25), we write

\[ A_x^{-1} A_x v(x,t) = A_x^{-1} A_x v(x,t) - A_x^{-1} A_t v(x,t) - A_x^{-1} S v(x,t) - A_x^{-1} N v(x,t), \]
\[ v(x,t) = \psi(x,t) - A_x^{-1} A_t v(x,t) - A_x^{-1} S v(x,t) - A_x^{-1} N v(x,t). \]

Here the function \( f(x,t) \) represents the terms arising from \( A_x^{-1} g(x,t) \), after using the given conditions. \( A_x^{-1} = \int \int f(x,t)dxdt \) is used as inverse operator for the second order partial differential equation.

In this method, the series solution \( v(x,t) \) is defined as:

\[ v(x,t) = \sum_{n=0}^{\infty} v_n(x,t), \]
\[ \sum_{n=0}^{\infty} v_n(x,t) = \psi(x,t) - L_x^{-1} A_t \sum_{n=0}^{\infty} v_n(x,t) - A_x^{-1} S \sum_{n=0}^{\infty} v_n(x,t) - A_x^{-1} N \sum_{n=0}^{\infty} v_n(x,t). \]

The non-linear term is expanded in adomian polynomials as:

\[ N \sum_{n=0}^{\infty} v_n(x,t) = \sum_{n=0}^{\infty} A_n. \]

Where the components \( v_0(x,t), v_1(x,t), v_2(x,t) \) ....... are periodically derived as:

\[ v_0(x,t) + v_1(x,t) + v_2(x,t) \ldots = \psi(x,t) - A_x^{-1} A_t (v_0(x,t) + v_1(x,t) + v_2(x,t) \ldots) - A_x^{-1} S (v_0(x,t) + v_1(x,t) + v_2(x,t) \ldots) - A_x^{-1} (A_0 + A_1 + A_2 \ldots). \]

To determine the components of the series \( v_0(x,t) + v_1(x,t) + v_2(x,t) \ldots \ldots \) it is important to note that ADM suggests that the zeroth component \( v_0(x,t) \) is usually defined by the function \( \psi(x,t) \) described above.

The formal recursive relation is defined as:
Using the inverse operator $L_x^{-1}$ on Eq. (33), we get

$$L_x^{-1}L_v(x,t) = L_x^{-1}(S_t + M_v + \frac{\partial v}{\partial t} - \alpha \frac{\partial v}{\partial x} + \frac{\partial^2 v}{\partial t^2} - 6\beta \frac{\partial v}{\partial x})^2 (\frac{\partial v}{\partial x})^4$$

Using the inverse operator, $L_x^{-1}$ on Eq. (33), we get

$$L_x^{-1}L_x v(x,t) = L_x^{-1} \left[ \frac{\partial (\partial^2 v)}{\partial t^2} \right] - \beta_1 L_x^{-1} \left[ \frac{\partial^2}{\partial t^2} \left( \frac{\partial^2 v}{\partial x^2} \right) \right] - 6\beta L_x^{-1} \left[ \frac{\partial v}{\partial x} \right]^2 \left( \frac{\partial v}{\partial x} \right)^4$$

$$L_x^{-1}L_x \Theta(x,t) = p_r L_x^{-1} \left[ \frac{\partial (\partial^2 v)}{\partial t^2} \right] - 2 \beta E_c \left[ \frac{\partial v}{\partial x} \right]^2 \left( \frac{\partial v}{\partial x} \right)^4$$

$$\sum_{n=0}^{\infty} v_n(x,t) = b_0 + b_1 x + \frac{x^2}{2} - 2\beta E_c \left[ \frac{\partial v}{\partial x} \right]^3 \sum_{n=0}^{\infty} u_n,$$
Similarly the series solution for temperature distribution can be obtained by using equations (49), (51) and (53) into equation (56).  
\[
\theta_1[x, t] = \frac{1}{60} [5 \beta_1 \epsilon C_s^2 (1 - x^4) + 4 \beta P_r \epsilon C_s^2 (1 - x^6)],  
\]  
\[
v_2[x, t] = \left[ \left( \frac{3 \beta S_s^2}{2} + \frac{5(M^2 - \omega^2)}{24} - \frac{\alpha \omega^2}{2} \right) \cos[t\omega] - \left( \frac{5 M \omega}{12} + \frac{3 \beta S_s^2}{2} + \frac{M \omega^2}{2} \right) \sin[t\omega] + \frac{61 M^2 S_t}{720} + \frac{49 \beta S_s^2}{60} + 2 \beta^2 S_t^2 \right] - \left[ \left( \frac{M^2}{4} + \frac{\omega^4}{4} + \frac{\alpha \omega^2}{2} \right) \cos[t\omega] + \left( \frac{M \omega (\alpha + 1)}{2} \right) \sin[t\omega] - \frac{5 M^2 S_t}{48} - \frac{M \omega S_t}{4} \right] x^2 - \left[ \left( \frac{M^2 - \omega^2}{2} - \frac{3 \beta S_s^2}{2} \right) \cos[t\omega] - \left( \frac{M \omega}{12} - \frac{3 \beta S_s^2}{2} \right) \sin[t\omega] + \frac{M^2 S_t}{48} - \frac{3 \beta S_s^2}{4} \right] x^4 - \left[ \frac{M^2 S_t}{720} - \frac{11 \beta S_s^2}{60} + 2 \beta^2 S_t^2 \right] x^6,  
\]  
Where \( \varphi_{11}, \ldots, \varphi_{17} \), are defined as 
\[
\varphi_{11} = P_r \epsilon C_s \left[ \left( \frac{5}{24} \beta_1 \omega^2 + \frac{4}{15} \beta S_t^3 - \frac{1}{6} S_t \right) M \cos[t\omega] + \left( \frac{4}{15} \beta \omega S_t^3 - \frac{5}{24} \beta_1 \omega^3 + \frac{1}{6} \omega S_t \right) \sin[t\omega] - \frac{13}{180} M S_t^2 \right] + \frac{2}{15} \beta S_t^4 - \frac{23}{210} M \beta S_t^4 - \frac{2}{7} \beta^2 S_t^6,  
\]  
\[
\varphi_{12} = -\frac{\alpha P_r \epsilon C_s}{6} (\omega^2 \cos[t\omega] + M \omega \sin[t\omega]),  
\]  
\[
\varphi_{13} = -\beta P_r \epsilon C_s (M \omega^2 \cos[t\omega] - \omega^3 \sin[t\omega]),  
\]  
\[
\varphi_{14} = \frac{\alpha P_r \epsilon C_s}{6} (\alpha \omega^2 \cos[t\omega] + M \omega \sin[t\omega]),  
\]  
\[
\varphi_{15} = \frac{24}{24} P_r \epsilon C_s (M \beta_1 \omega^2 \cos[t\omega] - \beta_1 \omega^3 \sin[t\omega] + 4 M \cos[t\omega] S_t - 4 \omega \sin[t\omega] S_t + 2 M \beta_1 S_t^2),  
\]  
\[
\varphi_{16} = \frac{24}{42} (24 M \beta \cos[t\omega] S_t^2 - 24 \beta \omega \sin[t\omega] S_t^2 + 12 S_t^4 + 12 M \beta S_t^4 - M S_t^2),  
\]  
\[
\varphi_{17} = \frac{24 P_r \epsilon C_s}{42} [\frac{2}{7} \beta^2 S_n^6 - M S_n^2].  
\]  
Inserting equations (48), (50) and (52) into equation (54) we get the series solution for fluid motion.  
\[
v[x, t] = v_0[x, t] + v_1[x, t] + v_2[x, t],  
\]  
Similarly the series solution for temperature distribution can be obtained by using equations (49), (51) and (53) into equation (56).  
\[
\theta[x, t] = \theta_0[x, t] + \theta_1[x, t] + \theta_2[x, t]  
\]  
\]  
\]  
\]  
\]  
\]  
\]  
\]  
\]

**Figure 2:** The velocity profile for magnetic parameter “M” when other parameters are kept fixed.  
\( \omega = 0.02, \alpha = 0.1, \beta = 0.2, S_t = 0.7, t = 0.4. \)
Figure 3: Velocity profile for stock number $S_t$, when other parameter is constant $\omega = 0.3, \alpha = 0.2, \beta = 0.5, M = 0.8, t = 0.4$.

Figure 4: The influence of stock number $S_t$, for temperature profile when other parameter is $\omega = 0.01, \alpha = 0.07, E_c = 1, P_r = 0.9, \beta_1 = 0.5, \beta = 0.01, M = 0.5, t = 0.1$.

Figure 5: The profile of temperature distribution of Prandtl number $P_r$, when $\omega = 0.02, \alpha = 0.07, E_c = 1, S_t = 0.9, \beta_1 = 0.5, \beta = 0.01, M = 0.5, t = 0.1$. 
RESULTS AND DISCUSSION

In the present study we discussed the velocity field and temperature of unsteady flow problems of magneto-hydrodynamics third grade fluid. ADM method has been used to obtain the solution of non-linear partial differential equations of temperature and velocity distribution. The effects of model parameters on velocity and temperature distribution have been discussed graphically. Figure 1 shows the geometry of the problem. Figure 2 shows the effect of $M$ on velocity field. We see that if the value of magnetic parameter $M$ increases, there is a decrease in the value of velocity profile because near the belt magnetic field as stronger. From the Figure 3 we observed that velocity increases when the value of stock number $S_t$ increases. Fig 4-6 are plotted to examine the effect of $E_c, P_r, A$ and $S_t$, on temperature distribution. Figure 4 shows the effect of $S_t$ on temperature distribution, there is an increase in the temperature if we increase the value of stock number $S_t$. Figure 5 shows the effect of $P_r$ on temperature field. From this figure we observed that temperature increases when the value of $P_r$ increases. Figure 6 is plotted to examine the effect of Eckert number $E_c$, on temperature distribution. We observe that the temperature is increasing by increasing Eckert number $E_c$.

REFERENCES


